



Datasheet V1.0



WISENSING GENERAL DESCRIPTION

The WiseSensing sensor nodes provide a reliable, easy-to-mount and cost effective solution, which is designed for dynamic and static structural health monitoring of large structures. They measure:

- 3-axes accelerations, with a sensitivity in frequency recognition of 0.5Hz at <1mg;
- polar angles inclinations, with a sensitivity of 0.02°;
- temperature, with a sensitivity of 0.5°C.

Data communications can be performed exploiting Zigbee protocol toward a dedicated Gateway, which sends data remotely either by Cellular or by Ethernet. Lora will be shortly available for only static and shock monitoring. The data can be sent either through FTP connection or through an HTTP POST request to a remote server, to be instantly available for analysis.

The main WiseSensing operation's parameters are reconfigurable from remote, such as:

- the range of measure and ODR for the accelerometer data acquisition;
- the axis/axes to acquire;
- the number of samples to acquire;
- the frequency of measurements during the day;
- the threshold and range for the shock accelerometer.

WiseSensing operation does not rely on any battery replacement, being powered by solar and vibrational energy.

Each node is capable of harvesting clean energy from the environment, transforming it into usable electrical energy in order to power sensors and communication stacks.

WiseSensing is IP67, ROHS 3 and UVrays resistant, so it is suitable to be installed outside without any additional protection.

WISENSENSING APPLICATION CASES

WiseSensing is designed in order to enable Structural Health Monitoring for large structures.

Its usage is recommended (but it is not limited) for monitoring:

- bridges, viaducts;
- aerial pipelines;
- <u>wind turbines, and in particular wind</u> <u>blades;</u>
- telecommunications antennas' poles;
- power grid poles.

In each of these cases, WiseSensing installation is easy and fast, and can be done either by screw-mounting (optionally exploiting a specifically designed mountingplate, that guarantees flatness and stability over rough sourfaces), or simply by gluing the sensor to the structure.

A Gateway with WiseSensing dedicated software for data collection needs to be additionally installed in the nearest proximity, and can be either powered directly or through solar energy.



WiseSensing powered by WISEP[®]WER

TECHNICAL SPECIFICATIONS

Prod	luct	refe	ren	ce

WiseSensing -PWR-COM-MO

PWR- power supply technology	COM- Communication WiFi technology	
VibPV: Non linear vibrational energy harvester transducer + Integrated solar panel (1W) + Li-Ion rechargeable battery (2.6Ah)	ZB : ZigBee radio LR : LoRa radio, coming soon	
PV : Integrated solar panel (1W) + Li-Ion rechargeable battery (2.6Ah)		
48V: external power supply of 48 Volts input.	CELL : 4G/LTE, coming soon	

MO - Mounting Option SM - Screw Mounting Lid SMO - Screw Mounting Lid Orthogonal

Example n°1: WiseSensing-VibPV-ZB-SM, WiseSensing with vibrational harvester PV cell and rechargeable battery, ZigBee wifi module and screw mounting lid option Example n°2: WiseSensing-PV-LR-SMO, WiseSensing with PV cell and rechargeable battery, LoRa wifi module and screw mounting lid option

Environmental and Mechanical Features		
	Waterproof casing	
Casing	Dimensions in mm (LxWxH): 120x120x50 mm	
	Weight in grams : 500 g	
IP Rating	IP67	
Operating Temperature	-30 °C to +75 °C	
Norms & Radio Certifications	CE Labelling Directive	
	FCC/IC (North America)	
	ETSI (Europe)	
	ROHS - Directive 2002/95/EC	



Sensors specification		
Accelerometer for SHM		
Accelerometer Technology	Low power MEMS technology	
Scalable measurement range	±2g / ±4g/ ±8g	
Measurement resolution	3.9 μg/digit @±2g , 7.8 μg/digit @±4g , 15.6 μg/digit @±8g	
Typical non-linearity	±0.1% FS	
Sensitivity change Vs temperature	±0.01%/°C (-40°C to +125°C)	
Zero-g level change vs temperature	±0.02 mg/°C (-40°C to +125°C)	
Typical zero-g level offset accuracy	±25 mg	
Noise spectral density @ BW 500Hz	25 μg/√Hz	
Acceler	ometer for Shock	
Accelerometer Technology	Low power MEMS technology	
Accelerometer Technology Scalable measurement range	Low power MEMS technology ±2g / ±4g/ ±8g	
Accelerometer Technology Scalable measurement range Measurement resolution	Low power MEMS technology ±2g / ±4g/ ±8g 1 mg/digit @±2g , 2 mg/digit @±4g , 4 mg/digit @±8g	
Accelerometer Technology Scalable measurement range Measurement resolution Typical non-linearity	Low power MEMS technology ±2g / ±4g/ ±8g 1 mg/digit @±2g , 2 mg/digit @±4g , 4 mg/digit @±8g ±0.5% FS	
Accelerometer TechnologyScalable measurement rangeMeasurement resolutionTypical non-linearitySensitivity change Vs temperature	Low power MEMS technology ±2g / ±4g/ ±8g 1 mg/digit @±2g , 2 mg/digit @±4g , 4 mg/digit @±8g ±0.5% FS ±0.05%/°C (-40°C to +85°C)	
Accelerometer TechnologyScalable measurement rangeMeasurement resolutionTypical non-linearitySensitivity change Vs temperatureZero-g level change vs temperature	Low power MEMS technology ±2g / ±4g/ ±8g 1 mg/digit @±2g , 2 mg/digit @±4g , 4 mg/digit @±8g ±0.5% FS ±0.05%/°C (-40°C to +85°C) ±0.5 mg/°C (-40°C to +85°C)	
Accelerometer TechnologyScalable measurement rangeMeasurement resolutionTypical non-linearitySensitivity change Vs temperatureZero-g level change vs temperatureTypical zero-g level offset accuracy	Low power MEMS technology ±2g / ±4g/ ±8g 1 mg/digit @ ±2g , 2 mg/digit @ ±4g , 4 mg/digit @ ±8g ±0.5% FS ±0.05%/°C (-40°C to +85°C) ±0.5 mg/°C (-40°C to +85°C) ±50 mg (Z axis) ±35 mg (X,Y axes)	
Accelerometer Technology Scalable measurement range Measurement resolution Typical non-linearity Sensitivity change Vs temperature Zero-g level change vs temperature Typical zero-g level offset accuracy	Low power MEMS technology ±2g / ±4g/ ±8g 1 mg/digit @±2g , 2 mg/digit @±4g , 4 mg/digit @±8g ±0.5% FS ±0.05%/°C (-40°C to +85°C) ±0.5 mg/°C (-40°C to +85°C) ±50 mg (Z axis) ±35 mg (X,Y axes) 920 µg/√Hz	
Accelerometer Technology Scalable measurement range Measurement resolution Typical non-linearity Sensitivity change Vs temperature Zero-g level change vs temperature Typical zero-g level offset accuracy Noise spectral density @ BW 100Hz	Low power MEMS technology $\pm 2g / \pm 4g / \pm 8g$ 1 mg/digit @ $\pm 2g$, 2 mg/digit @ $\pm 4g$, 4 mg/digit @ $\pm 8g$ $\pm 0.5\%$ FS $\pm 0.05\%$ °C (-40°C to +85°C) ± 0.5 mg/°C (-40°C to +85°C) ± 50 mg (Z axis) ± 35 mg (X,Y axes) 920 µg/ \sqrt{Hz} emperature	
Accelerometer Technology Scalable measurement range Measurement resolution Typical non-linearity Sensitivity change Vs temperature Zero-g level change vs temperature Typical zero-g level offset accuracy Noise spectral density @ BW 100Hz	Low power MEMS technology ±2g / ±4g/ ±8g 1 mg/digit @±2g , 2 mg/digit @±4g , 4 mg/digit @±8g ±0.5% FS ±0.05%/°C (-40°C to +85°C) ±0.5 mg/°C (-40°C to +85°C) ±50 mg (Z axis) ±35 mg (X,Y axes) 920 µg/√Hz emperature from -40°C to +125°C	



RF Specifications			
ZigBee [©]			
Wireless Protocol Stack	ZigBee [©]		
WSN Topology	Star		
Data rate	250 Kbits/s		
RF Characteristics	ISM 2.4GHz		
TX Power	+8 dBm		
Receiver Sensitivity	-103 dBm		
Maximum Radio Range	600m (Line of Sight), 40m (Non Line of Sight)		
RF Options			
Gateway ZigBee [©]	XGI-20CZ7-E00-W0 [WiFi + ETH0] XGI-20CZ7-EU7-W0 [WiFi + ETH0 + Cellular]		

Power supply		
Energy havesting	Vibrational and PV harvesting battery charger	
	Integrated Lithium-ion battery solar and vibrational battery charger :	
Environmental battery charger	 Overvoltage Protection, Overcurrent/Short-Circuit Protection, Undervoltage Protection Battery Temperature monitoring 	

Over-the-air configuration (OTAC) parameters		
ZigBee [©]		
ODR SHM Accelerometer	from 31.25 Hz up to 500 Hz	
Acquisition interval	from evrey hour up to every 8 hour	
Samples to acquire	from 1024 up to 32768	
Data transmission	1 axis , 2axes or 3 axes	
Shock detection threshold	from 1.1g up to 8g	



Current consumption @ 3 V			
During data acquisition	from 3mA up to 5mA		
During ZigBee [©] TX	30mA @ 8dBm		
During ZigBee [©] RX	10mA		
During LoRa [™] TX	45 mA @14dbm		
During LoRa [™] RX	10mA		
During Cellular TX	134 mA @23dBm		
During Cellular RX/Listening	18mA @3.3V		
During sleep mode (shock ON)	7μΑ		



INCLINOMETER TEST

A test was performed, mounting the sensor on a micrometric screw with minimum step of 0.02°.

The progressive inclination measured by the accelerometer was calculated, in degrees, by applying the following geometrical rules to the RMS accelerations on the three measurement axes:

$$\Theta = \frac{180^{\circ}}{\pi} \arcsin\left(\frac{a_{y}}{a_{RMS}}\right)$$
$$\Phi = \frac{180^{\circ}}{\pi} \arctan\left(\frac{a_{x}}{a_{z}}\right)$$

The results, when changing the inclination progressively with steps of 0.02° on Θ , are illustrated in Table 1 for the measured Θ and Φ acquiring 1024 samples with ODR = 500Hz, and when changing the inclination on Φ under the same conditions, in Table 2.

After repeating the test with 32768 samples, the sensitivity over the inclination angle was demonstrated to lower to **0.001 deg**.

This is due o the fact that a single measure of rms acceleration on one axis is given by computing the rms of the samples in one measurement for the same axis, and therefore the precision of a single rms measurement increases by increasing the number of samples.

Table 1: Sensitivity test for inclinometer. 1024 samples with ODR = 500Hz. Inclination on Θ

Experimental inclination on Θ	⊖ measured	Experimental inclination on Φ	Φ measured
$0.02^{\circ} \pm 0.005^{\circ}$	$0.023^{\circ} \pm 0.003^{\circ}$	$0.000 \circ \pm 0.005^{\circ}$	0.0027 ± 0.0015°
0.04 ± 0.005°	0.040 ± 0.003°	$0.000 \circ \pm 0.005^{\circ}$	0.0017 ± 0.0015°
0.06 ± 0.005°	0.064 ± 0.003°	$0.000 \circ \pm 0.005^{\circ}$	0.0005 ± 0.0015°
0.08 ± 0.005°	0.085 ± 0.003°	0.000 ° ± 0.005°	0.0016 ± 0.0015°

Table 1: Sensitivity test for inclinometer. 1024 samples with ODR = 500Hz. Inclination on Φ

Experimental inclination on Θ	Θ measured	Experimental inclination on Φ	Φ measured
$0.000^{\circ} \pm 0.005^{\circ}$	-0.003° ± 0.003°	$0.060^{\circ} \pm 0.005^{\circ}$	0.063 ± 0.002°
$0.000 \pm 0.005^{\circ}$	-0.002 ± 0.003°	$0.080^{\circ} \pm 0.005^{\circ}$	0.084 ± 0.002°
$0.000 \pm 0.005^{\circ}$	-0.001 ± 0.003°	0.10 ° ± 0.005°	0.107 ± 0.002°
0.000 ± 0.005°	-0.007 ± 0.003°	0.12 ° ± 0.005°	0.129 ± 0.002°



ACCELEROMETER TEST

The accelerometer was excited through a TIRA-vib TV51144 shacker connected to a function generator and a power amplifier, as shown in Figure 1. At first it was driven with a signal of rms = 1 mg having three main frequency components of 3, 5, 7 Hz with white overimposed with rms amplitude noise 10 smaller approximately times in acceleration. Then, the same signal was used, but the frequencies where shifted of 0.5Hz (smaller shifts were not achievable).

WiseSensing was configured to acquire 32768 samples at 125Hz.

In the Figures below the experimental set-up and the power spectrums of the two measured accelerations are shown, demonstrating the capability of the accelerometer to distinguish 0.5Hz shifts in frequencies even in noisy environments.

The peak at around 36Hz that is clearly visible in the spectrum, and whose detection is fully repeatible over different acquisitions, is due to the rotary motor of the voltage amplificator that is governing the shacker, and that is laying on the same table.



Figure 1 : Experimental set-up for testing WiseSensing frequency resolution in noisy environments



Figure 2 : Time series and power spectrum of the recorded acceleration for a 0.5 Hz shift in the main frequency components

Energy Harvesting Technologies



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ULTERIORI INFORMAZIONI

I prodotti della linea WiseSensing sono **certificati**:

- CE Labelling Directive
- FCC/IC (North America)
- ETSI (Europe)
- ROHS Directive 2002/95/EC

WiseSensing può essere soggetto di customizzazione, previa attenta valutazione da parte del team tecnico di Wisepower.

Per ulteriori informazioni consultare il sito **www.wisepower.it** o telefonare al numero **+39 075 584 7210**.

L'ufficio tecnico di Wisepower Srl si trova in **Via Zeffirino Farina 4**, **06123, Perugia (PG), Italia**.

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